

NAG Toolbox for MATLAB

e02bc

1 Purpose

e02bc evaluates a cubic spline and its first three derivatives from its B-spline representation.

2 Syntax

```
[s, ifail] = e02bc(lamda, c, x, left, 'ncap7', ncap7)
```

3 Description

e02bc evaluates the cubic spline $s(x)$ and its first three derivatives at a prescribed argument x . It is assumed that $s(x)$ is represented in terms of its B-spline coefficients c_i , for $i = 1, 2, \dots, \bar{n} + 3$ and (augmented) ordered knot set λ_i , for $i = 1, 2, \dots, \bar{n} + 7$, (see e02ba), i.e.,

$$s(x) = \sum_{i=1}^q c_i N_i(x).$$

Here $q = \bar{n} + 3$, \bar{n} is the number of intervals of the spline and $N_i(x)$ denotes the normalized B-spline of degree 3 (order 4) defined upon the knots $\lambda_i, \lambda_{i+1}, \dots, \lambda_{i+4}$. The prescribed argument x must satisfy

$$\lambda_4 \leq x \leq \lambda_{\bar{n}+4}.$$

At a simple knot λ_i (i.e., one satisfying $\lambda_{i-1} < \lambda_i < \lambda_{i+1}$), the third derivative of the spline is in general discontinuous. At a multiple knot (i.e., two or more knots with the same value), lower derivatives, and even the spline itself, may be discontinuous. Specifically, at a point $x = u$ where (exactly) r knots coincide (such a point is termed a knot of multiplicity r), the values of the derivatives of order $4 - j$, for $j = 1, 2, \dots, r$, are in general discontinuous. (Here $1 \leq r \leq 4$; $r > 4$ is not meaningful.) You must specify whether the value at such a point is required to be the left- or right-hand derivative.

The method employed is based upon:

- (i) carrying out a binary search for the knot interval containing the argument x (see Cox 1978),
- (ii) evaluating the nonzero B-splines of orders 1, 2, 3 and 4 by recurrence (see Cox 1972a and Cox 1978),
- (iii) computing all derivatives of the B-splines of order 4 by applying a second recurrence to these computed B-spline values (see de Boor 1972),
- (iv) multiplying the fourth-order B-spline values and their derivative by the appropriate B-spline coefficients, and summing, to yield the values of $s(x)$ and its derivatives.

e02bc can be used to compute the values and derivatives of cubic spline fits and interpolants produced by e02ba.

If only values and not derivatives are required, e02bb may be used instead of e02bc, which takes about 50% longer than e02bb.

4 References

Cox M G 1972a The numerical evaluation of B-splines *J. Inst. Math. Appl.* **10** 134–149

Cox M G 1978 The numerical evaluation of a spline from its B-spline representation *J. Inst. Math. Appl.* **21** 135–143

de Boor C 1972 On calculating with B-splines *J. Approx. Theory* **6** 50–62

5 Parameters

5.1 Compulsory Input Parameters

1: **lamda(ncap7) – double array**

lamda(j) must be set to the value of the j th member of the complete set of knots, λ_j , for $j = 1, 2, \dots, \bar{n} + 7$.

Constraint: the **lamda**(j) must be in nondecreasing order with **lamda**(ncap7 – 3) > **lamda**(4).

2: **c(ncap7) – double array**

The coefficient c_i of the B-spline $N_i(x)$, for $i = 1, 2, \dots, \bar{n} + 3$. The remaining elements of the array are not used.

3: **x – double scalar**

The argument x at which the cubic spline and its derivatives are to be evaluated.

Constraint: **lamda**(4) $\leq x \leq$ **lamda**(ncap7 – 3).

4: **left – int32 scalar**

Specifies whether left- or right-hand values of the spline and its derivatives are to be computed (see Section 3). Left- or right-hand values are formed according to whether **left** is equal or not equal to 1.

If x does not coincide with a knot, the value of **left** is immaterial.

If $x =$ **lamda**(4), right-hand values are computed.

If $x =$ **lamda**(ncap7 – 3), left-hand values are formed, regardless of the value of **left**.

5.2 Optional Input Parameters

1: **ncap7 – int32 scalar**

Default: The dimension of the arrays **lamda**, **c**. (An error is raised if these dimensions are not equal.)

$\bar{n} + 7$, where \bar{n} is the number of intervals of the spline (which is one greater than the number of interior knots, i.e., the knots strictly within the range λ_4 to $\lambda_{\bar{n}+4}$ over which the spline is defined).

Constraint: **ncap7** ≥ 8 .

5.3 Input Parameters Omitted from the MATLAB Interface

None.

5.4 Output Parameters

1: **s(4) – double array**

s(j) contains the value of the $(j - 1)$ th derivative of the spline at the argument x , for $j = 1, 2, 3, 4$. Note that **s**(1) contains the value of the spline.

2: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

ncap7 < 8, i.e., the number of intervals is not positive.

ifail = 2

Either **lamda**(4) \geq **lamda**(**ncap7** – 3), i.e., the range over which $s(x)$ is defined is null or negative in length, or **x** is an invalid argument, i.e., **x** < **lamda**(4) or **x** > **lamda**(**ncap7** – 3).

7 Accuracy

The computed value of $s(x)$ has negligible error in most practical situations. Specifically, this value has an **absolute** error bounded in modulus by $18 \times c_{\max} \times \text{machine precision}$, where c_{\max} is the largest in modulus of c_j, c_{j+1}, c_{j+2} and c_{j+3} , and j is an integer such that $\lambda_{j+3} \leq x \leq \lambda_{j+4}$. If c_j, c_{j+1}, c_{j+2} and c_{j+3} are all of the same sign, then the computed value of $s(x)$ has **relative** error bounded by $18 \times \text{machine precision}$. For full details see Cox 1978.

No complete error analysis is available for the computation of the derivatives of $s(x)$. However, for most practical purposes the absolute errors in the computed derivatives should be small.

8 Further Comments

The time taken is approximately linear in $\log(\bar{n} + 7)$.

Note: the function does not test all the conditions on the knots given in the description of **lamda** in Section 5, since to do this would result in a computation time approximately linear in $\bar{n} + 7$ instead of $\log(\bar{n} + 7)$. All the conditions are tested in e02ba, however.

9 Example

```
lamda = [0;
        0;
        0;
        0;
        1;
        3;
        3;
        3;
        3;
        4;
        4;
        6;
        6;
        6;
        6;
        6];
c = [10;
     12;
     13;
     15;
     22;
     26;
     24;
     18;
     14;
     12;
     0;
     0;
     0;
     0;
     0];
x = 0;
```

```
left = int32(1);  
[s, ifail] = e02bc(lamda, c, x, left)
```

```
s =  
    10.0000  
     6.0000  
    -10.0000  
    10.6667  
ifail =  
        0
```
